- Introduction
  - band join
    - » R.A c1 < S.B < R.A + c2
  - partitioned band join
    - » goal : minimize number of disk accesses
  - Sort-merge band join
    - » combining final merge phase with join phase
- Partitioned band join algorithm
  - choose partition size
    - » randomly sampling R
    - » select partition elements
      - ✓ Kolmogorov test statistic [W.J.Conover 71]
    - » number of partitions
  - perform partitioning without sorting
    - » use range-vector
    - » overlap
      - √Li c1 < S.B < Hi + c2
  - compute subjoins between Ri and Si
    - » binary search on sorted inner partition

- Uniprocessor environment
  - equal relation sizes : figure 1.
  - relation sizes differ : figure 2.
  - GP : grace partitioned band join algorithm
  - HP : hybrid partitioned band join algorithm

- Multiprocessor environment
  - parallel hybrid partitioned band join
    - » each processor randomly samples
    - » coordinator determines partitioning elements
    - » each processr re-distributes local fragment
  - problem
    - » how to correctly and efficiently sample inner relation in parallel to determine partitioning elements
- Experiment results
  - scaleup : slight increase in response time
    - » duplicate initiating tasks
    - » effects of short-circuiting messages diminish
    - » skew in size of subjoins
      - $\checkmark$  sampling time vs. execution time
  - speedup : not perfectly linear
    - » overhead of scheduling operators
    - » same factors as cases in scaleup

- Conclusions
  - hash-based equijoin vs. partitioned band join
    - » hash bucket vs. sort inner partition
    - » table lookup vs. binary search
    - » sampling overhead
  - suitable cases
    - » a fraction of relation fits in memory
    - » relation sizes are different

- Introduction
  - multiple-query scheduling
    - » optimize a set of queries together
    - » share some operations within queries
    - » examples : shared build or shared probe
- Sharing operators
  - select
    - » apply each predicate in turn for each tuple
  - join
    - » hybrid hash-join algorithm
      - $\checkmark$  sharing build phase
    - » multiprocessor join algorithm
      - $\checkmark$  joins involving same relation on different join attributes
  - sort, aggregates, group-by, duplicate elimination

- Batch scheduling
  - aim : find a global schedule for all queries without violating partial order constraints
  - workload : single hash join queries
  - cost metric : total number of I/Os
- Algorithms
  - Non-sharing algorithm
  - Exhaustive algorithm
    - » select a global ordering of queries
    - » choose building relations
    - » determine order of flush of relations in memory
  - Heuristic algorithms
    - » select next building relation
      - ✓ ranking functions : ProbSize, ProbSubBuild,
        - ProbDivBuild
    - » select next relation to flush
      - ✓ Largest, LowRank, HighRank

- Simulation
  - shared-nothing model
  - comparison
    - » ratio of batch size to number of relations : figure 1.
      - ✓ memory requirement
      - $\checkmark$  replication tuples
    - » sensitivity to system memory : figure 2.
      - $\checkmark$  naive algorithm gains due to parallelism
    - » non-uniform relation usage : figure 3.
      - ✓ skewed distribution has higher potential for sharing
- Future work